

# NATIONAL SENIOR CERTIFICATE

**GRADE 12** 

## **SEPTEMBER 2020**



# **ELECTRICAL TECHNOLOGY: POWER SYSTEMS**

**MARKS: 200** 

TIME: 3 hours

This question paper consists of 13 pages, including a 2-page formula sheet.

### **INSTRUCTIONS AND INFORMATION**

- 1. This question paper consists of SIX questions.
- 2. Answer ALL the questions.
- 3. Show ALL calculations and round off answers correctly to TWO decimal places.
- 4. Number the answers correctly according to the numbering system used in this question paper.
- 5. Sketches and diagrams must be large, neat and FULLY LABELLED.
- 6. You may use a non-programmable calculator.
- 7. Calculations must include:
  - 7.1 Formulae and manipulations where needed
  - 7.2 Correct replacement of values
  - 7.3 Correct answers and relevant units where applicable
- 8. A formula sheet is provided at the end of this question paper.
- 9. Write neatly and legibly.



### **QUESTION 1: OCCUPATIONAL HEALTH AND SAFETY**

- 1.1 Define the term *accident* with reference to the Occupational Health and Safety Act, 1993 (Act 85 of 1993). (2)
- 1.2 Explain TWO general duties of employees in the workplace. (2)
- 1.3 State TWO unsafe conditions in a school workshop that can cause an accident. (2)
- 1.4 Briefly explain a *third-degree burn*. (2)
- 1.5 State TWO functions of a health and safety representative. (2) [10]

### **QUESTION 2: RLC**

- 2.1 Explain the phase relationship between current and voltage in the following AC circuit:
  - 2.1.1 A pure capacitive circuit (2)
  - 2.1.2 A pure inductive circuit (2)
  - 2.1.3 A resistive circuit (2)
- 2.2 Refer to the circuit diagram FIGURE 2.2 below and answer the questions that follow.

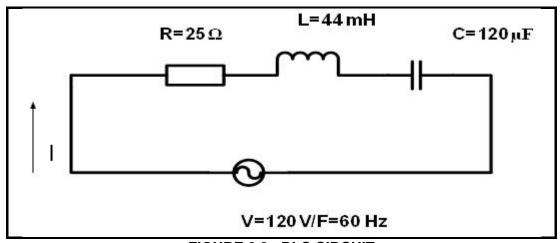


FIGURE 2.2: RLC CIRCUIT

### Calculate the:

2.2.1 Inductive reactance (3)

2.2.2 Capacitive reactance (3)

2.2.3 Impedance of the circuit (3)

2.2.4 Total current flow through the circuit (3)

(3)

(2)

(2) **[50]** 

- 2.3 Explain how the value of the capacitive reactance will be affected if the supply frequency is increased.
- 2.4 A parallel circuit in FIGURE 2.5 consists of a capacitor that draws a current of 4 A, an inductor that draws a current of 6 A and a resistor that draws a current of 5 A. All the components are connected to 240 V / 50 Hz supply.

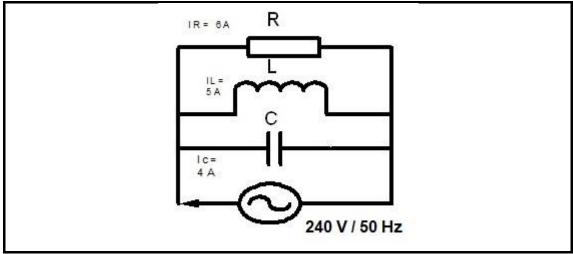


FIGURE 2.5: RLC PARALLEL CIRCUIT

### Calculate:

2.6.2

2.6.3

The size of the inductor

The circuit resistance

2.4.1 The total current through the circuit (3)2.4.2 The phase angle (3)2.4.3 The inductive reactance (3)2.4.4 The capacitive reactance (3)2.5 A parallel RLC circuit consists of a 10  $\Omega$  resistor and a 0,05  $\mu$ F and a 0,2 H inductor connected across a 120 V supply. Calculate the: 2.5.1 Resonant frequency (3)2.5.2 Q-factor (4) 2.5.3 Bandwidth (3)2.6 A series RLC tuned circuit has a resonant frequency of 95 MHz and a bandwidth of 200 kHz. The capacitor is 2,5 pF and the wire used to wind the coil has zero resistance. Calculate: 2.6.1 The Q factor of the circuit (3)

### **QUESTION 3: THREE-PHASE AC GENERATION**

- 3.1 Draw a neat, labelled schematic representation of a star connected power system. Show all voltages and phasors. (4)
- 3.2 State the functions of the following meters:
  - 3.2.1 Kilowatt-hour meter (2)
  - 3.2.2 Wattmeter (1)
- 3.3 Name TWO disadvantages of a single-phase system when compared to a three-phase system. (2)
- 3.4 Refer to FIGURE 3.4 below and answer the questions that follow.

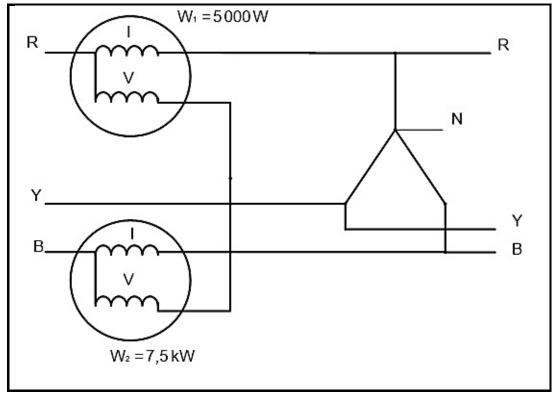


FIGURE 3.4

- 3.4.1 Describe how the two watt meters are connected to the star system. (3)
- 3.4.2 Calculate the total power of the three-phase system. (3)
- 3.4.3 Calculate the power factor of the system. (5)

(1) **[40]** 

3.5 A 380 V three-phase system is star connected to a lagging load. The input power is 25 kW and the load causes a lagging power factor of 0,8.

Given:  $V_1 = 380 \text{ V}$ 

 $P_{IN} = 25 \text{ kW}$  $\cos \theta = 0.8$ 

### Calculate:

- 3.5.1 The phase voltage (3)
- 3.5.2 The line current to the load (3)
- 3.5.3 The reactive power (3)
- 3.6 Explain why the power supply to dwellings cannot be connected in delta. (2)
- 3.7 Describe how a low power factor affects an AC electrical power system. (4)
- 3.8 Discuss the following stages of three-phase AC generation from the supplier to the consumer.
  - 3.8.1 Generation (2)
  - 3.8.2 Transmission (2)
  - 3.8.3 Mention ONE type of consumer that receives electricity from intermediate substations.

### **QUESTION 4: THREE-PHASE TRANSFORMERS**

- 4.1 Name TWO types of transformer configurations available when manufacturing three-phase transformers. (2)
- 4.2 Mention the reasons for mounting the magnetic circuit and windings of power transformers in mineral oil. (2)
- 4.3 Mention TWO types of protection devices used for the protection of transformers. (2)
- 4.4 State TWO cooling methods used for oil-immersed transformers. (2)
- 4.5 Name the type of induction that takes place between the primary and secondary coils of a transformer. (1)
- A 20 kVA delta-star transformer has a primary voltage of 6 kV and a 4.6 secondary voltage of 1 000 V. The losses amount to 160 W and the power factor is 0,88.

Given: S = 20 kVA

 $V_{IP} = 6 \text{ kV}$  $V_{1.S} = 500 \text{ V}$ 

 $P_{LOSSES} = 160 \text{ W}$ 

 $\cos \theta = 0.88$ 

### Calculate:



4.6.1 The secondary line current (3)

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- 4.6.2 The transformation ratio (6)
- 4.6.3 The input power (3)
- 4.6.4 The efficiency of the transformer (3)
- 4.7 Explain why transformers have a better efficiency than motors. (3)
- 4.8 Explain why a transformer only operates with an AC supply. (3)[30]

### QUESTION 5: THREE-PHASE MOTORS AND STARTERS

- 5.1 Define the term *slip* with reference to a three-phase AC induction motor. (2)
- 5.2 Give TWO reasons why the rotor of an induction motor is *skewed*. (2)
- 5.3 One of the electrical tests performed on the stator of a three-phase motor is the insulation resistance test between windings and earth.
  - 5.3.1 State the reasons for performing this test. (2)
  - 5.3.2 Write down the accepted value for a motor to pass this test. (1)
- 5.4 State the main function of a three-phase motor starter. (1)
- 5.5 Refer to the control circuit in FIGURE 5.5 and answer the questions that follow.

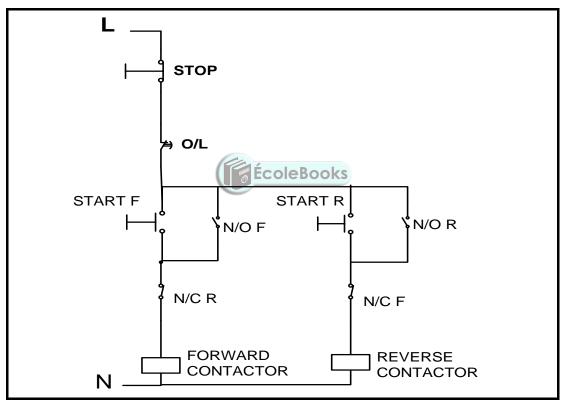


FIGURE 5.5: CONTROL CIRCUIT

- 5.5.1 Identify the starter shown in FIGURE 5.5. (1)
- 5.5.2 Describe the function of the two normally closed contacts in the circuit. (2)
- 5.5.3 Explain what happens if the circuit is energised and the start forward button is pressed. (4)
- 5.5.4 Describe the function of the overload contact in the circuit. (2)
- 5.5.5 Explain how a faulty N/O R that remains stuck in the closed position, would affect the operation of the starter. (4)

- 5.6 A manual sequence starter has the following sequence:
  - Motor 1 must start before Motor 2
  - Each motor must have independent overload protection
  - A stop button controls both motors

Draw the control circuit of the sequence starter.

(6)

5.7 A delta connected three-phase motor has a phase voltage of 380 V with a power factor of 0,866. The line current is 25 A when the motor is connected to the supply. Calculate the input power to the motor.

Given:  $V_{PH} = 380 \text{ V}$ 

$$\cos \theta = 0.866$$

$$I_{L} = 25 \text{ A} \tag{3}$$

5.8 Define the term *synchronous speed* of a motor.

(2)

5.9 A three-phase motor with 24 poles has a synchronous speed of 1 200 rpm. Determine the percentage slip if the rotor speed is 1 140 rpm.

Given: Poles = 24

$$N_S = 1 \ 200 \ rpm$$
  
 $N_P = 1 \ 140 \ rpm$ 

(3)

5.10 Mention THREE types of information that can be found on the nameplate of a motor.

(3)

5.11 A 110 V / 60 Hz three-phase motor is connected to a supply in a factory in South Africa. State with a reason if the motor will operate. (2)

[40]

### QUESTION 6: PROGRAMMABLE LOGIC CONTROLLERS (PLC's)

6.1 Choose a description from COLUMN B that matches with the term in COLUMN A. Write only the letter (A–E) in COLUMN B next to the question number (6.1.1-6.1.5) in COLUMN A, for example 6.1.6 G.

COLUMN A		COLUMN B	
6.1.1	Input device	Α	Brain of the PLC
6.1.2	Hardware	В	Disadvantage of hardwiring
6.1.3	Processor	С	Physical parts and components
6.1.4	Output	D	Sensor
6.1.5	Bulky	Е	Motor

 $(5 \times 1)$ (5)

- 6.2 Explain why software is installed.
  - (3)
- 6.3 Refer to FIGURE 6.3 below and answer the questions that follow.

INPUT A	INPUT B	OUTPUT (F)
0	0	1
0	Car 1	0
1	FØleRook:	0
1	1	0

FIGURE 6.3: TRUTH TABLE

- 6.3.1 Draw the ladder diagram that this truth table represents. (3)
- 6.3.2 Draw the logic gate symbol that this truth table represents. (3)
- 6.4 Define an opto-isolator. (3)
- 6.5 State TWO applications of light sensors. (2)
- 6.6 Describe the function of the timer used in PLC programs. (2)

6.7 Refer to FIGURE 6.7 and draw a logic ladder diagram that executes the same function as the one in FIGURE 6.7.

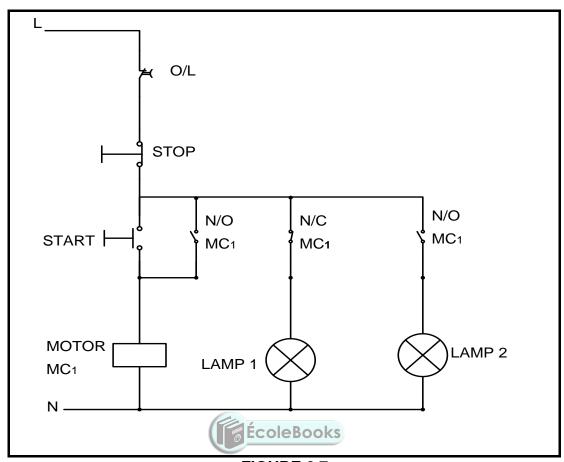


FIGURE 6.7

**NOTE**: The circuit is energised.

(9) **[30]** 

**TOTAL: 200** 

### **FORMULA SHEET**

### **RLC-CIRCUITS**

$$X_L = 2\pi f L$$
 and  $X_C = \frac{1}{2\pi f C}$  
$$f_r = \frac{1}{2\pi \sqrt{LC}}$$

$$f_r = \frac{1}{2\pi\sqrt{LC}}$$

$$P = VI \cos \theta$$

$$I_T = I_R = I_L = I_C$$

$$Z = \sqrt{R^2 + (X_L - X_C)^2}$$

$$V_L = I \times X_L$$
 and  $V_C = I \times X_C$ 

$$\begin{array}{lll} P = VI\cos\theta \\ & \textbf{SERIES} \\ & I_T = I_R = I_L = I_C \\ & Z = \sqrt{R^2 + (X_L - X_C)^2} \\ & V_L = I \times X_L & \text{and} & V_C = I \times X_C \\ & V_T = IZ & \text{and} & V_T = \sqrt{V_R^2 + (V_L - V_C)^2} \\ & \cot\theta = \frac{R}{Z} & \text{and} & \cos\theta = \frac{V_R}{V_T} \\ & Q = \frac{X_L}{Z} = \frac{X_C}{Z} = \frac{V_L}{V_S} = \frac{V_C}{V_S} = \frac{1}{R} \sqrt{\frac{L}{C}} \\ & P = S\cos\theta \\ & Q = \frac{R}{Z} & \text{and} & I_C = \frac{V_C}{V_C} \\ & I_R = \frac{V_R}{R} \\ & I_L = \frac{V_L}{X_L} & \text{and} & I_C = \frac{V_C}{X_C} \\ & I_T = \sqrt{I_R^2 + (I_L - I_C)^2} \\ & \cos\theta = \frac{I_R}{I_T} \\ & Q = \frac{X_L}{Z} = \frac{X_C}{Z} = \frac{V_L}{V_S} = \frac{V_C}{V_S} = \frac{1}{R} \sqrt{\frac{L}{C}} \\ & Q = \frac{X_L}{Z} = \frac{X_C}{Z} = \frac{V_L}{V_S} = \frac{V_C}{V_S} = \frac{1}{R} \sqrt{\frac{L}{C}} \\ & Q = \frac{X_L}{Z} = \frac{X_C}{Z} = \frac{V_L}{V_S} = \frac{V_C}{V_S} = \frac{1}{R} \sqrt{\frac{L}{C}} \\ & Q = \frac{X_L}{Z} = \frac{X_C}{Z} = \frac{V_L}{V_S} = \frac{V_C}{V_S} = \frac{1}{R} \sqrt{\frac{L}{C}} \\ & Q = \frac{X_L}{Z} = \frac{X_C}{Z} = \frac{V_L}{V_S} = \frac{V_C}{V_S} = \frac{1}{R} \sqrt{\frac{L}{C}} \\ & Q = \frac{X_L}{Z} = \frac{X_C}{Z} = \frac{V_L}{V_S} = \frac{V_C}{V_S} = \frac{1}{R} \sqrt{\frac{L}{C}} \\ & Q = \frac{X_L}{Z} = \frac{X_C}{Z} = \frac{V_L}{V_S} = \frac{V_C}{V_S} = \frac{1}{R} \sqrt{\frac{L}{C}} \\ & Q = \frac{X_L}{Z} = \frac{X_C}{Z} = \frac{V_L}{V_S} = \frac{V_C}{V_S} = \frac{1}{R} \sqrt{\frac{L}{C}} \\ & Q = \frac{X_L}{Z} = \frac{X_C}{Z} = \frac{V_L}{V_S} = \frac{V_C}{V_S} = \frac{1}{R} \sqrt{\frac{L}{C}} \\ & Q = \frac{X_L}{Z} = \frac{X_C}{Z} = \frac{V_L}{V_S} = \frac{V_C}{V_S} = \frac{1}{R} \sqrt{\frac{L}{C}} \\ & Q = \frac{X_L}{Z} = \frac{X_C}{Z} = \frac{V_L}{V_S} = \frac{V_C}{V_S} = \frac{1}{R} \sqrt{\frac{L}{C}} \\ & Q = \frac{X_L}{Z} = \frac{X_C}{Z} = \frac{V_L}{V_S} = \frac{V_C}{V_S} = \frac{1}{R} \sqrt{\frac{L}{C}} \\ & Q = \frac{X_L}{Z} = \frac{X_C}{Z} = \frac{V_L}{V_S} = \frac{V_C}{V_S} = \frac{1}{R} \sqrt{\frac{L}{C}} \\ & Q = \frac{X_L}{Z} = \frac{X_C}{Z} = \frac{V_L}{V_S} = \frac{V_C}{V_S} = \frac{1}{R} \sqrt{\frac{L}{C}} \\ & Q = \frac{X_L}{Z} = \frac{X_C}{Z} = \frac{V_L}{V_S} = \frac{V_C}{V_S} = \frac{1}{R} \sqrt{\frac{L}{C}} \\ & Q = \frac{X_L}{Z} = \frac{X_L}{Z}$$

$$\cos \theta = \frac{R}{Z}$$
 and  $\cos \theta = \frac{V_R}{V_T}$ 

$$Q = \frac{X_L}{Z} = \frac{X_C}{Z} = \frac{V_L}{V_S} = \frac{V_C}{V_S} = \frac{1}{R} \sqrt{\frac{L}{C}}$$

$$V_S = V_R = V_L = V_C$$

$$I_R = \frac{V_R}{R}$$

$$I_L = \frac{V_L}{X_L}$$
 and  $I_C = \frac{V_C}{X_C}$ 

$$I_{\rm T} = \sqrt{I_{\rm R}^2 + (I_{\rm L} - I_{\rm C})^2}$$

$$\cos \theta = \frac{I_R}{I_T}$$

$$Q = \frac{X_L}{Z} = \frac{X_C}{Z} = \frac{V_L}{V_S} = \frac{V_C}{V_S} = \frac{1}{R} \sqrt{\frac{L}{C}}$$

### THREE-PHASE AC GENERATION

### **STAR**

STAR 
$$V_L = \sqrt{3} \times V_{PH} \quad \text{and} \quad V_{PH} = I_{PH} \times Z_{PH}$$
 
$$I_L = I_{PH}$$

$$I_L = I_{PH}$$

$$V_L = V_{PH} \qquad \text{ and } \ V_{PH} = I_{PH} \times Z_{PH}$$

$$I_{\rm L} = \sqrt{3} \times I_{\rm PH}$$

$$S = \sqrt{3}V_LI_I$$

$$Q = \sqrt{3}V_L I_L \sin \theta$$

$$P = \sqrt{3}V_L I_L \cos \theta$$

$$P = S \cos \theta$$

$$\cos \theta = \frac{P}{S}$$

### TWO-WATTMETER METHOD

$$P_{\rm T} = W_1 + W_2$$

$$\tan\theta = \sqrt{3} \left( \frac{W_1 - W_2}{W_1 + W_2} \right)$$

### **FORMULA SHEET**

### **THREE-PHASE TRANSFORMERS**

### **STAR**

$$V_L = \sqrt{3} \times V_{PH}$$
 and  $I_L = I_{PH}$ 

### **DELTA**

$$V_L = V_{PH} \qquad \text{ and } I_L = \sqrt{3} \times I_{PH}$$

### **POWER**

$$S = \sqrt{3}V_L I_I$$

$$Q = \sqrt{3}V_L I_L \sin \theta$$

$$P = \sqrt{3}V_{I}I_{I}\cos\theta$$

$$P = S \cos \theta$$

$$\cos \theta = \frac{P}{S}$$

$$\eta = \frac{P_{INPUT} - P_{LOSSES}}{P_{INPUT}} \times 100$$

T. Ratio = 
$$\frac{V_{PHP}}{V_{PHS}} = \frac{N_P}{N_S} = \frac{I_{PHS}}{I_{PHP}}$$

# THREE-PHASE MOTORS AND STARTERS

### **STAR**

$$V_L = \sqrt{3} \times V_{PH} \quad \text{and} \ I_L = I_{PH}$$

### **DELTA**

$$V_{\rm L} = V_{\rm PH}$$
 and  $I_{\rm L} = \sqrt{3} \times I_{\rm PH}$ 

### **POWER**

$$S = \sqrt{3}V_LI_L$$

$$Q = \sqrt{3}V_L I_L \sin\theta$$

$$P = \sqrt{3}V_L I_L \cos \theta$$

$$P = S \cos \theta$$



$$\eta = \frac{P_{INPUT} - P_{LOSSES}}{P_{INPUT}} \times 100$$

### **MOTOR SPEED**

$$n_s = \frac{60 \times f}{p}$$

$$Slip = \frac{n_s - n_r}{n_s} \times 100\%$$